## A nonconfocal generator of involutive systems and Levy hierarchy

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# A non-confocal generator of involutive systems and Levy hierarchy 

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#### Abstract

In this paper, a new non-confocal generator of involutive systems is obtained, and the relation between it and Levy equation hierarchy is discussed. Furthermore, the representation of the solution for the Levy hierarchy is given.


## 1. Introduction

To find a new integrable system is an important subject [1,2] in soliton theory and integrability theory. However, whether a Hamiltonian system is completely integrable depends on whether the N -involutive system exists or not; almost all involutive systems already acquired by nonlinearized eigenvalue problems [3] are reduced to the so-called confocal involutive systems [4-14], whose generators are

$$
T_{k}=\sum_{\substack{j=1 \\ j \neq k}}^{N} \frac{\left(p_{k} q_{j}-p_{j} q_{k}\right)^{2}}{\alpha_{k}-\alpha_{j}} \quad k=1,2, \ldots, N
$$

A natural problem is to find non-confocal generators, so that essential new integrable system can be obtained.

In this paper, a new generator of the non-confocal involutive system $\tilde{G}_{k}$ is found:

$$
\begin{equation*}
\tilde{G}_{k}=\sum_{\substack{j=1 \\ j \neq k}}^{N} \frac{\lambda_{k}^{2} p_{k}^{2} q_{j}^{2}+\lambda_{j}^{2} p_{j}^{2} q_{k}^{2}-\left(\lambda_{k}^{2}+\lambda_{j}^{2}\right) \dot{p}_{k} p_{j} q_{k} q_{j}}{\lambda_{k}^{2}-\lambda_{j}^{2}}+\frac{\lambda_{j} p_{j}^{2} q_{k}^{2}-\lambda_{k} p_{k}^{2} q_{j}^{2}}{\lambda_{k}+\lambda_{j}} \tag{1.1}
\end{equation*}
$$

We prove that the Hamiltonian system $\left(R^{2 N}, \mathrm{~d} P \wedge \mathrm{~d} Q=\sum_{j=1}^{N} \mathrm{~d} p_{j} \wedge \mathrm{~d} q_{j}, H\right)$ is completely integrable in the Liouville sense, where

$$
\begin{equation*}
H=\frac{1}{2}\left(\left\langle A^{2} P, Q\right\rangle+\langle P, Q\rangle^{2}-\langle A Q, Q\rangle\langle P, Q\rangle-\langle A P, P\rangle\right) \tag{1.2}
\end{equation*}
$$

$A=\operatorname{diag}\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{N}\right),\langle\cdot, \cdot\rangle$ are a standard inner product in $R^{N}, Q=$ $\left(q_{1}, q_{2}, \ldots, q_{N}\right)^{\mathrm{T}}, P=\left(p_{1}, p_{2}, \ldots, p_{N}\right)^{\mathrm{T}}$. Furthermore, the relation between the completely integrable Hamiltonian system $\left(R^{2 N}, \mathrm{~d} P \wedge \mathrm{~d} Q, H\right)$ and Levy equation hierarchy $[15,16]$ is discussed; the solutions of the Levy hierarchy are generated by the solutions of the completely integrable systems.

## 2. The non-confocal generator and the finite-dimensional complete integrable Hamiltonian systems [17]

Let $P=\left(p_{1}, p_{2}, \ldots, p_{N}\right)^{\mathrm{T}}$ and $Q=\left(q_{1}, q_{2}, \ldots, q_{N}\right)^{\mathrm{T}}$ be the basic coordinate functions in $R^{2 N}$. The Poisson bracket of two smooth functions $F_{1}$ and $F_{2}$ in the symplectic
space $\left(R^{2 N}, \mathrm{~d} P \wedge \mathrm{~d} Q=\sum_{j=1}^{N} \mathrm{~d} p_{j} \wedge \mathrm{~d} q_{j}\right)$ is defined as [17]

$$
\begin{equation*}
\left(F_{1}, F_{2}\right)=\sum_{j=1}^{N} \frac{\partial F_{1}}{\partial q_{j}} \frac{\partial F_{2}}{\partial p_{j}}-\frac{\partial F_{1}}{\partial p_{j}} \frac{\partial F_{2}}{\partial q_{j}} \tag{2.1}
\end{equation*}
$$

which satisfies the Leibnitz rule:

$$
\left(F_{1} F_{2}, F_{3}\right)=F_{1}\left(F_{2}, F_{3}\right)+F_{2}\left(F_{1}, F_{3}\right)
$$

where $F_{3}$ is the smooth function in the symplectic space ( $R^{2 N}, \mathrm{~d} P \wedge \mathrm{~d} Q$ ). $F_{1}$ and $F_{2}$ is called an involution if $\left(F_{1}, F_{2}\right)=0$.

The Hamiltonian canonical equation of the smooth function $F$ in the symplectic space ( $R^{2 N}, \mathrm{~d} P \wedge \mathrm{~d} Q$ ) is defined as [17]

$$
\left.\begin{array}{l}
p_{j t}=\left(p_{j}, F\right)=-\partial F / \partial q_{J}  \tag{2.2}\\
q_{j t}=\left(q_{j}, F\right)=\partial F / \partial p_{j}
\end{array}\right\} \quad j=1,2, \ldots, N .
$$

Theorem 2.1. $\left(\tilde{G}_{n}, \tilde{G}_{k}\right)=0, \quad n, k=1,2, \ldots, N$.
Proof. Evidently $\left(\tilde{G}_{k}, \tilde{G}_{k}\right)=0$, let

$$
\begin{aligned}
& n \neq k \quad A_{k j}=\lambda_{j} p_{j}^{2} q_{k}^{2}-\lambda_{k} p_{k}^{2} q_{j}^{2} \\
& B_{k j}=\lambda_{k}^{2} p_{k}^{2} q_{j}^{2}+\lambda_{j}^{2} q_{k}^{2} p_{j}^{2}-\left(\lambda_{k}^{2}+\lambda_{j}^{2}\right) p_{k} q_{j} q_{k} p_{j} \\
& \sum_{n}^{\prime}=\sum_{\substack{i=1 \\
i \neq n}}^{N} \quad \sum_{k}^{\prime}=\sum_{\substack{j=1 \\
j \neq k}}^{N} \quad \sum_{j}^{\prime \prime}=\sum_{\substack{j=1 \\
j \neq k, n}}^{N} \quad \sum_{i}=\sum_{\substack{i=1 \\
i \neq n, k}}^{N}
\end{aligned}
$$

then

$$
\left(B_{k n}, B_{n k}\right)=0 \quad\left(A_{k n}, A_{n k}\right)=0
$$

and

$$
\begin{aligned}
\left(\tilde{G}_{n}, \tilde{G}_{k}\right)= & \left(\sum_{n}^{\prime}\left(\frac{B_{n i}}{\lambda_{n}^{2}-\lambda_{i}^{2}}+\frac{A_{n i}}{\lambda_{n}+\lambda_{i}}\right), \sum_{k}^{\prime}\left(\frac{B_{k j}}{\lambda_{k}^{2}-\lambda_{j}^{2}}+\frac{A_{k j}}{\lambda_{k}+\lambda_{j}}\right)\right) \\
= & \left(\sum_{n}^{\prime} \frac{B_{n i}}{\lambda_{n}^{2}-\lambda_{i}^{2}}, \sum_{k}^{\prime} \frac{B_{k j}}{\lambda_{k}^{2}-\lambda_{j}^{2}}\right)+\left(\sum_{n}^{\prime} \frac{B_{n i}}{\lambda_{n}^{2}-\lambda_{i}^{2}}-\sum_{k}^{\prime} \frac{A_{k j}}{\lambda_{k}+\lambda_{j}}\right) \\
& +\left(\sum_{n}^{\prime} \frac{A_{n i}}{\lambda_{n}+\lambda_{i}}, \sum_{k}^{\prime} \frac{A_{k j}}{\lambda_{k}+\lambda_{j}}\right)+\left(\sum_{n}^{\prime} \frac{A_{n i}}{\lambda_{n}+\lambda_{i}}, \sum_{k}^{\prime} \frac{B_{k j}}{\lambda_{k}^{2}-\lambda_{j}^{2}}\right) .
\end{aligned}
$$

Through direct calculation, we have

$$
\begin{aligned}
&\left(\sum_{n}^{\prime} \frac{B_{n i}}{\lambda_{n}^{2}-\lambda_{t}^{2}}, \sum_{k}^{\prime} \frac{B_{k j}}{\lambda_{k}^{2}-\lambda_{j}^{2}}\right)=\left(\sum_{i}^{\prime \prime} \frac{B_{n i}}{\lambda_{n}^{2}-\lambda_{i}^{2}}, \sum_{j}^{\prime \prime} \frac{B_{k j}}{\lambda_{k}^{2}-\lambda_{j}^{2}}\right) \\
&+\left(\frac{B_{n k}}{\lambda_{n}^{2}-\lambda_{k}^{2}}, \sum_{j}^{\prime \prime} \frac{B_{k j}}{\lambda_{k}^{2}-\lambda_{j}^{2}}\right)+\left(\sum_{i}^{\prime \prime} \frac{B_{n i}}{\lambda_{n}^{2}-\lambda_{i}^{2}}, \frac{B_{k n}}{\lambda_{k}^{2}-\lambda_{n}^{2}}\right)=0 .
\end{aligned}
$$

Similarly
$\left(\sum_{n}^{\prime} \frac{B_{n i}}{\lambda_{n}^{2}-\lambda_{i}^{2}}, \sum_{k}^{\prime} \frac{A_{k j}}{\lambda_{k}+\lambda_{j}}\right)+\left(\sum_{n}^{\prime} \frac{A_{n i}}{\lambda_{n}+\lambda_{i}}, \sum_{k}^{\prime} \frac{A_{k j}}{\lambda_{k}+\lambda_{j}}\right)+\left(\sum_{n}^{\prime} \frac{A_{n i}}{\lambda_{n}+\lambda_{i}}, \sum_{k}^{\prime} \frac{B_{k j}}{\lambda_{k}^{2}-\lambda_{j}^{2}}\right)=0$.
Thus $\left(\tilde{G}_{n}, \tilde{G}_{k}\right)=0, \quad n, k=1,2, \ldots, N$.

Theorem 2.2. Set

$$
Q_{z}(\xi, \eta)=\left\langle\left(z I-A^{2}\right)^{-1} \xi, \eta\right\rangle=\sum_{k=1}^{N} \frac{\xi_{k} \eta_{k}}{z-\lambda_{k}^{2}}
$$

where $I$ denotes the unit matrix, then the generalizing function of $\tilde{G}_{k}$ is

$$
\sum_{k=1}^{N} \frac{\tilde{G}_{k}}{z-\lambda_{k}^{2}}=\left|\begin{array}{cc}
Q_{z}(A P, P) & Q_{z}(P, Q) \\
Q_{z}\left(A^{2} P, Q\right) & Q_{z}(A Q, Q)
\end{array}\right|
$$

Proof. Since

$$
Q_{z}(\xi, \eta)=\sum_{k=1}^{N} \frac{\xi_{k} \eta_{k}}{z-\lambda_{k}^{2}}
$$

and

$$
\frac{1}{\left(z-\lambda_{k}^{2}\right)\left(z-\lambda_{j}^{2}\right)}=\frac{1}{\left(z-\lambda_{k}^{2}\right)\left(\lambda_{k}^{2}-\lambda_{j}^{2}\right)}+\frac{1}{\left(z-\lambda_{\jmath}^{2}\right)\left(\lambda_{j}^{2}-\lambda_{k}^{2}\right)}
$$

the required result is obtained through direct calculation.

Theorem 2.3. Let

$$
E_{k}=\lambda_{k}^{2} p_{k} q_{k}-\lambda_{k} p_{k}^{2}+\langle P, Q\rangle p_{k} q_{k}-\langle P, Q\rangle \lambda_{k} q_{k}^{2}-\tilde{G}_{k}
$$

then $\left\{E_{k}, k=1,2, \ldots, N\right\}$ is an $N$-involutive system.

Proof. Evidently $\left(E_{n}, E_{n}\right)=0$, let $n \neq k$, then through direct calculation, we have

$$
\begin{aligned}
& \left(-\lambda_{n} p_{n}^{2},\langle P, Q\rangle p_{k} q_{k}\right)+\left(\langle P, Q\rangle p_{n} q_{n},-\lambda_{k} p_{k}^{2}\right)+\left(-\lambda_{n} p_{n}^{2},-\tilde{G}_{k}\right)+\left(-\tilde{G}_{n},-\lambda_{k} p_{k}^{2}\right)=0 \\
& \begin{array}{l}
\left(-\lambda_{n} p_{n}^{2},-\langle P, Q\rangle \lambda_{k} q_{k}^{2}\right)+\left(-\langle P, Q\rangle \lambda_{n} q_{n}^{2},-\lambda_{k} p_{k}^{2}\right)+\left(\lambda_{n}^{2} p_{n} q_{n},-\tilde{G}_{k}\right)+\left(-\tilde{G}_{n}, \lambda_{k}^{2} p_{k} q_{k}\right)=0 \\
\begin{array}{l}
\left(\langle P, Q\rangle p_{n} q_{n},-\tilde{G}_{k}\right)+\left(-\tilde{G}_{n},\langle P, Q\rangle p_{k} q_{k}\right)=0
\end{array} \\
\begin{array}{l}
\left(\langle P, Q\rangle p_{n} q_{n},-\lambda_{k}\langle P, Q\rangle q_{k}^{2}\right)+\left(-\langle P, Q\rangle \lambda_{n} q_{n}^{2},\langle P, Q\rangle p_{k} q_{k}\right) \\
\\
\quad+\left(-\lambda_{n}\langle P, Q\rangle q_{n}^{2},-\tilde{G}_{k}\right)+\left(-\tilde{G}_{n},-\lambda_{k}\langle P, Q\rangle q_{k}^{2}\right)=0 \\
\begin{array}{ll}
\left(\langle P, Q\rangle, p_{k} q_{k}\right)=0 & \quad\left(p_{n} q_{n}, p_{k} q_{k}\right)=0 \\
\left(p_{n}^{2}, p_{k} q_{k}\right)=0 & \left(q_{n}^{2}, p_{k} q_{k}\right)=0 .
\end{array}
\end{array} .
\end{array} l
\end{aligned}
$$

From theorem 2.1, $\left(\tilde{G}_{n}, \tilde{G}_{k}\right)=0$, thus $\left(E_{n}, E_{k}\right)=0, \quad n, k=1,2, \ldots, N$.

Theorem 2.4. The Hamiltonian system (2.3) by definition (1.2) is finite-dimensional and completely integrable in the Liouville sense.

$$
\left.\begin{array}{l}
p_{j x}=-\partial H / \partial q_{j}  \tag{2.3}\\
q_{j x}=\partial H / \partial p_{j}
\end{array}\right\} \quad j=1,2, \ldots, N .
$$

Proof. From theorem 2.3, $\left(E_{n}, E_{k}\right)=0, \quad n, k=1,2, \ldots, N$, and through direct calculation, we have

$$
\left(H, E_{k}\right)=0 \quad k=1,2, \ldots, N .
$$

The required result is obtained.
From theorem 2.2, let $|z|>\max \left\{\left|\lambda_{1}^{2}\right|,\left|\lambda_{2}^{2}\right|, \ldots,\left|\lambda_{N}^{2}\right|\right\}$, then

$$
\left(z-\lambda_{k}^{2}\right)^{-1}=\sum_{m=0}^{\infty} z^{-(m+1)} \lambda_{k}^{2 m}
$$

so that

$$
\begin{aligned}
& Q_{z}(\xi, \eta)=\sum_{m=0}^{\infty} z^{-(m+1)}\left\langle A^{2 m} \xi, \eta\right\rangle \\
& \sum_{k=1}^{N} \frac{\tilde{G}_{k}}{z-\lambda_{k}^{2}}=\sum_{m=0}^{\infty} \sum_{i+j=m-1} z^{-(m+1)}\left|\begin{array}{cc}
\left\langle A^{2 i+1} P, P\right\rangle & \left\langle A^{2 i} P, Q\right\rangle \\
\left\langle A^{2 j+2} P, Q\right\rangle & \left\langle A^{2 j+1} Q, Q\right\rangle
\end{array}\right|
\end{aligned}
$$

thus

$$
\sum_{k=1}^{N} \tilde{G}_{k} \lambda_{k}^{2 m}=\sum_{j=1}^{m}\left|\begin{array}{cc}
\left\langle A^{2 j-1} P, P\right\rangle & \left\langle A^{2 j} P, Q\right\rangle \\
\left\langle A^{2 m-2 j} P, Q\right\rangle & \left\langle A^{2 m-2 j+1} Q, Q\right\rangle
\end{array}\right| .
$$

Furthermore

$$
\begin{equation*}
\sum_{k=1}^{N} \frac{1}{2} E_{k} \lambda_{k}^{2 m}=H_{m} \tag{2.4}
\end{equation*}
$$

where

$$
\begin{gather*}
H_{m}=\frac{1}{2}\left\langle A^{2 m+2} P, Q\right\rangle-\frac{1}{2}\left\langle A^{2 m+1} P, P\right\rangle+\frac{1}{2}\langle P, Q\rangle\left\langle A^{2 m} P, Q\right\rangle-\frac{1}{2}\langle P, Q\rangle\left\langle A^{2 m+1} Q, Q\right\rangle \\
+\frac{1}{2} \sum_{j=1}^{m} \left\lvert\, \begin{array}{cc}
\left\langle A^{2 J} P, Q\right\rangle & \left\langle A^{2 j-1} Q, Q\right\rangle \\
\left\langle A^{2 m-2 j+1} P, P\right\rangle & \left\langle A^{2 m-2 j} P, Q\right\rangle
\end{array} .\right. \tag{2.5}
\end{gather*}
$$

By theorem 2.3, we have

$$
\begin{align*}
\left(H_{m}, H_{n}\right) & =\left(\sum_{k=1}^{N} \frac{1}{2} E_{k} \lambda_{k}^{2 m}, \sum_{j=1}^{N} \frac{1}{2} E_{j} \lambda_{j}^{2 n}\right) \\
& =\sum_{k=1}^{N} \sum_{j=1}^{N} \frac{1}{4} \lambda_{k}^{2 m} \lambda_{j}^{2 n}\left(E_{k}, E_{j}\right)=0 \quad m, n=1,2,3, \ldots \tag{2.6}
\end{align*}
$$

By theorem 2.4, we have

$$
\begin{equation*}
\left(H, H_{m}\right)=0 \quad m=1,2, \ldots \tag{2.7}
\end{equation*}
$$

Theorem 2.5. The Hamiltonian system defined by (2.8) is finite-dimensional and completely integrable in the Liouville sense.
$p_{j t_{m}}=-\frac{\partial H_{m}}{\partial q_{j}}$

$$
\begin{equation*}
q_{j t_{m}}=\frac{\partial H_{m}}{\partial p_{j}} \tag{2.8}
\end{equation*}
$$

$$
m=1,2, \ldots, \quad j=1,2, \ldots, N
$$

where $H_{m}$ is defined by (2.5).
Proof. From (2.4), we have

$$
\left(H_{m}, E_{k}\right)=0 \quad k=1,2, \ldots, N
$$

so that theorem 2.5 holds.

## 3. Relationship with the Levy equation hierarchy

Now, we consider the following eigenvalue problem:

$$
\left[\begin{array}{l}
y_{1}  \tag{3.1}\\
y_{2}
\end{array}\right]_{x}=\left[\begin{array}{cc}
-\frac{1}{2}\left(\lambda^{2}+u+v\right) & \lambda u \\
-\lambda & \frac{1}{2}\left(\lambda^{2}+u+v\right)
\end{array}\right]\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right]=M\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right]
$$

where $u$ and $v$ are called potentials, $\lambda$ is the eigenparameter.
Let $\partial=\partial / \partial x, \partial \partial^{-1}=\partial^{-1} \partial=1$, and the operators $K$ and $J$ take the following form:

$$
K=\left[\begin{array}{cc}
-(\partial u+u \partial) & -\partial^{2}-v \partial+\partial u  \tag{3.2}\\
\partial^{2}+u \partial-\partial v & \partial v+v \partial
\end{array}\right] \quad J=\left[\begin{array}{ll}
0 & \partial \\
\partial & 0
\end{array}\right] .
$$

We define Lenart's sequence $G_{j}, j=0,1,2, \ldots$, by means of the recursion relations
$K G_{j-1}=J G_{j} \quad j=0,1,2, \ldots, \quad G_{j}=\left[\begin{array}{l}c_{j} \\ b_{j}\end{array}\right] \quad G_{-1}=\left[\begin{array}{l}0 \\ 1\end{array}\right] \quad j=1,2, \ldots$
Set

$$
\bar{N}_{j}=\left[\begin{array}{cc}
\frac{1}{2}\left(\lambda^{2}+u+v\right)\left(c_{j}-b_{j}\right)-\frac{1}{2}\left(c_{j x}-b_{j x}\right) & \lambda\left(u b_{j}-u c_{j}-b_{j x}\right)  \tag{3.4}\\
\lambda\left(c_{j}-b_{j}\right) & -\frac{1}{2}\left(\lambda^{2}+u+v\right)\left(c_{j}-b_{j}\right)+\frac{1}{2}\left(c_{j x}-b_{j x}\right)
\end{array}\right] .
$$

Directly computing, we obtain

$$
\begin{align*}
& \bar{N}_{j x}+\bar{N}_{j} M-M \bar{N}_{j} \\
&= {\left[\begin{array}{cc}
-\frac{1}{2} & \lambda \\
0 & \frac{1}{2}
\end{array}\right]\left[\left(-\partial u-u \partial,-\partial^{2}-v \partial+\partial u\right) G_{j}-\lambda^{2}(0, \partial) G_{j}\right] } \\
&+\left[\begin{array}{cc}
-\frac{1}{2} & 0 \\
0 & \frac{1}{2}
\end{array}\right]\left[\left(\partial^{2}+u \partial-\partial v, \partial v+v \partial\right) G_{j}-\lambda^{2}(\partial, 0) G_{j}\right] . \tag{3.5}
\end{align*}
$$

Further, we take

$$
N_{m}=\sum_{j=0}^{m} \bar{N}_{j-1} \lambda^{2 m-2 j} \quad m=0,1,2, \ldots
$$

From (3.3), (3.4) and (3.5), we have the following theorem.
Theorem.3.1. The $m$ th-order Levy equation

$$
\left[\begin{array}{l}
u  \tag{3.6}\\
v
\end{array}\right]_{t_{m}}=J G_{m}=K G_{m-1}
$$

is equivalent to the zero-curvature equation

$$
M_{t_{m}}=N_{m x}-\left[M, N_{m}\right]=N_{m x}+N_{m} M-M N_{m}
$$

which is the compatible condition for the following Lax pair:

$$
\begin{align*}
& {\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right]_{x}=M\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right] .}  \tag{3.1}\\
& {\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right]_{\mathrm{t}_{m}}=N_{m}\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right] .} \tag{3.7}
\end{align*}
$$

Example. By (3.3)

$$
\begin{aligned}
G_{0}=\left[\begin{array}{c}
v \\
u
\end{array}\right] \quad J^{-1} & =\left[\begin{array}{cc}
0 & \partial^{-1} \\
\partial^{-1} & 0
\end{array}\right] \quad G_{1}=J^{-1} K G_{0}=\left[\begin{array}{c}
v_{x}-v^{2}+2 u v \\
-u_{x}+u^{2}-2 u v
\end{array}\right] \\
& {\left[\begin{array}{l}
u \\
v
\end{array}\right]_{t_{1}} }
\end{aligned}=\left[\begin{array}{c}
\left(-u_{x}+u^{2}-2 u v\right)_{x} \\
\left(v_{x}-v^{2}+2 u v\right)_{x}
\end{array}\right] .
$$

has the Lax pair

$$
\begin{gathered}
{\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right]_{x}=M\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right]} \\
{\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right]_{t_{1}}=\left[\begin{array}{cc}
-\frac{1}{2}\left(\lambda^{2}+u+v\right)\left(\lambda^{2}-v+u\right)-\frac{1}{2}\left(v_{x}-u_{x}\right) & \lambda\left(u^{2}-u v-u_{x}+\lambda^{2} u\right) \\
-\lambda^{3}+\lambda(v-u) & \frac{1}{2}\left(\lambda^{2}+u+v\right)\left(u-v+\lambda^{2}\right)+\frac{1}{2}\left(v_{x}-u_{x}\right)
\end{array}\right]} \\
\\
\times\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right] .
\end{gathered}
$$

Remark. From (3.2) and (3.6), let $\Phi=K J^{-1}$, then

$$
\Phi=\left[\begin{array}{cc}
-\partial-v+\partial u \partial^{-1} & -\partial u \partial^{-1}-u \\
\partial v \partial^{-1}+v & \partial+u-\partial v \partial^{-1}
\end{array}\right]
$$

is the hereditary operator of the Levy hierarchy [16], and we have
$\left[\begin{array}{l}u \\ v\end{array}\right]_{t_{m}}=K G_{m-1}=K J^{-1} J G_{m-1}=K J^{-1} K G_{m-2}=\ldots=\left(K J^{-1}\right)^{m} J G_{0}=\Phi^{m}\left[\begin{array}{l}u_{x} \\ v_{x}\end{array}\right]$
so that equation (3.6) is called an $m$ th-order Levy equation.
Now, let $\lambda_{j}$ and $\left(p_{j}, q_{j}\right)^{\mathrm{T}}$ be the eigenvalue and eigenfunction of (3.1) under certain boundary conditions, say, periodic or decaying to zero at infinity

$$
\left[\begin{array}{l}
p_{j}  \tag{3.1}\\
q_{j}
\end{array}\right]_{x}=\left[\begin{array}{cc}
-\frac{1}{2}\left(\lambda_{j}^{2}+u+v\right) & \lambda_{j} u \\
-\lambda_{j} & \frac{1}{2}\left(\lambda_{j}^{2}+u+v\right)
\end{array}\right]\left[\begin{array}{l}
p_{j} \\
q_{j}
\end{array}\right] \quad j=1,2, \ldots, N .
$$

Then in the normal way we have [6]:

$$
\operatorname{grad} \lambda_{J}=\left[\begin{array}{c}
\delta \lambda_{j} / \delta u \\
\delta \lambda_{j} / \delta v
\end{array}\right]=\left[\begin{array}{c}
p_{j} q_{j}-\lambda_{j} q_{j}^{2} \\
p_{j} q_{j}
\end{array}\right]
$$

By (3.2), we obtain

$$
K\left[\begin{array}{c}
p_{j} q_{j}-\lambda_{j} q_{j}^{2}  \tag{3.8}\\
p_{j} q_{j}
\end{array}\right]=\lambda_{j}^{2} J\left[\begin{array}{c}
p_{j} q_{j}-\lambda_{j} q_{j}^{2} \\
p_{j} q_{j}
\end{array}\right] \quad j=1,2, \ldots, N .
$$

Consider the following constraint [6]:

$$
G_{0}=\left[\begin{array}{c}
v  \tag{3.9}\\
u
\end{array}\right]=\left[\begin{array}{c}
\langle P, Q\rangle-\langle A Q, Q\rangle \\
\langle P, Q\rangle
\end{array}\right] .
$$

From (3.3), (3.8) and (3.9), we have

$$
c_{j}=\left\langle A^{2 j} P, Q\right\rangle-\left\langle A^{2 j+1} Q, Q\right\rangle \quad b_{j}=\left\langle A^{2} P, Q\right\rangle \quad j=0,1,2, \ldots
$$

In the case of the constraint condition (3.9), the Lax pair (3.1), (3.7) of the $m$ th-order Levy equation are nonlinearized respectively as follows:

$$
\begin{array}{lll}
p_{j x}=-\frac{\partial H}{\partial q_{j}} & q_{j x}=\frac{\partial H}{\partial p_{j}} & j=1,2, \ldots, N \\
p_{j t_{m}}=-\frac{\partial H_{m}}{\partial q_{j}} & q_{j t_{m}}=\frac{\partial H_{m}}{\partial p_{j}} & j=1,2, \ldots, N \tag{3.11}
\end{array}
$$

where $H$ is defined by (1.2), $H_{m}$ is defined by (2.5).
According to theorem 2.4 and equations (2.6), (2.7), the Hamiltonian canonical systems (3.10) and (3.11) are completely integrable in the Liouville sense; and (3.10) and (3.11) are compatible [17]; therefore the Hamiltonian phase $g_{H}^{x}$ and $g_{H_{m}}^{t_{m}}$ are commutable. Now, we arbitrarily choose an initial value $(P(0,0), Q(0,0))^{\mathrm{T}}$; set

$$
\left[\begin{array}{l}
P\left(x, t_{m}\right)  \tag{3.12}\\
Q\left(x, t_{m}\right)
\end{array}\right]=g_{H}^{x} g_{H_{m}}^{t_{m}}\left[\begin{array}{l}
P(0,0) \\
Q(0,0)
\end{array}\right]=g_{H_{m}}^{t_{m}} g_{H}^{x}\left[\begin{array}{l}
P(0,0) \\
Q(0,0)
\end{array}\right]
$$

then (3.12) is called an involutive solution of the Hamiltonian canonical systems (3.10) and (3.11). We thus obtain the following theorem.

Theorem 3.2. Suppose $\left(P\left(x, t_{m}\right), Q\left(x, t_{m}\right)\right)^{T}$ is an involutive solution of (3.10) and (3.11), then

$$
\begin{aligned}
& v=\left\langle P\left(x, t_{m}\right), Q\left(x, t_{m}\right)\right\rangle-\left\langle A Q\left(x, t_{m}\right), Q\left(x, t_{m}\right)\right\rangle \\
& u=\left\langle P\left(x, t_{m}\right), Q\left(x, t_{m}\right)\right\rangle
\end{aligned}
$$

becomes the solution of the $m$ th-order Levy equation (3.6).

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